

CEMRACS,
July 19-23, 2021

Approximation and learning with tensor networks

Part II: Approximation theory of tree tensor networks

Anthony Nouy

Centrale Nantes, Laboratoire de Mathématiques Jean Leray

- 1 Approximation tools based on tree tensor networks
- 2 Universality, Proximality and Expressivity
- 3 Choice of tensor formats
- 4 Approximation classes of tree tensor networks

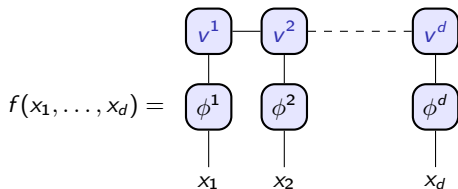
- 1 Approximation tools based on tree tensor networks
- 2 Universality, Proximality and Expressivity
- 3 Choice of tensor formats
- 4 Approximation classes of tree tensor networks

Approximation tools based on tree tensor networks

For the approximation of a target function $u(x_1, \dots, x_d)$, a first approach is to introduce subspaces $V_{N_\nu}^\nu$ of finite dimension (e.g. polynomials, splines, wavelets...) and consider tensor networks $f \in \mathcal{T}_r^T(V_N)$ with

$$V_N = V_{N_1}^1 \otimes \dots \otimes V_{N_d}^d$$

e.g. with the tensor train format



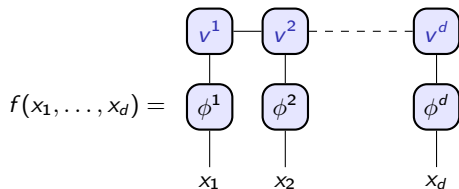
with ϕ^ν a feature map associated with $V_{N_\nu}^\nu$.

Approximation tools based on tree tensor networks

For the approximation of a target function $u(x_1, \dots, x_d)$, a first approach is to introduce subspaces $V_{N_\nu}^\nu$ of finite dimension (e.g. polynomials, splines, wavelets...) and consider tensor networks $f \in \mathcal{T}_r^T(V_N)$ with

$$V_N = V_{N_1}^1 \otimes \dots \otimes V_{N_d}^d$$

e.g. with the tensor train format



with ϕ^ν a feature map associated with $V_{N_\nu}^\nu$.

Spaces $V_{N_\nu}^\nu$ have to be well chosen, e.g. polynomials for analytic functions, splines with a degree adapted to the regularity of the target function...

An **approximation tool** $\Phi = (\Phi_n)_{n \in \mathbb{N}}$ is then defined by

$$\Phi_n = \{f \in \mathcal{T}_r^T(V_N) : N \in \mathbb{N}^d, r \in \mathbb{N}^T, \text{compl}(f) \leq n\}.$$

The dimensions N and the ranks r are **free parameters**, and $\text{compl}(\cdot)$ is some **complexity measure**.

Approximation tools based on tree tensor networks

An alternative is to rely on **tensorization** of functions. A d -variate function f is identified with a tensor

$$\mathbf{f} = T_{b,d}(f) \in (\mathbb{R}^b)^{\otimes Ld} \otimes (\mathbb{R}^{[0,1]})^{\otimes d}$$

such that

$$f(x_1, \dots, x_d) = \mathbf{f}(i_1^1, \dots, i_d^1, \dots, i_1^L, \dots, i_d^L, y_1, \dots, y_d) \quad \text{with} \quad x_\nu = b^{-L}([i_\nu^1 \dots i_\nu^L]_b + y_\nu).$$

Approximation tools based on tree tensor networks

An alternative is to rely on **tensorization** of functions. A d -variate function f is identified with a tensor

$$\mathbf{f} = T_{b,d}(f) \in (\mathbb{R}^b)^{\otimes Ld} \otimes (\mathbb{R}^{[0,1]})^{\otimes d}$$

such that

$$f(\mathbf{x}_1, \dots, \mathbf{x}_d) = \mathbf{f}(i_1^1, \dots, i_d^1, \dots, i_1^L, \dots, i_d^L, y_1, \dots, y_d) \quad \text{with} \quad x_\nu = b^{-L}([i_\nu^1 \dots i_\nu^L]_b + y_\nu).$$

Then we consider functions whose **tensorization at resolution L** are in the **tensor space**

$$\mathbf{V}_L = (\mathbb{R}^b)^{\otimes Ld} \otimes \mathcal{S}^{\otimes d}$$

with $\mathcal{S} \subset \mathbb{R}^{[0,1]}$ some subspace of univariate functions.

Approximation tools based on tree tensor networks

An alternative is to rely on **tensorization** of functions. A d -variate function f is identified with a tensor

$$\mathbf{f} = T_{b,d}(\mathbf{f}) \in (\mathbb{R}^b)^{\otimes Ld} \otimes (\mathbb{R}^{[0,1]})^{\otimes d}$$

such that

$$f(\mathbf{x}_1, \dots, \mathbf{x}_d) = \mathbf{f}(i_1^1, \dots, i_d^1, \dots, i_1^L, \dots, i_d^L, y_1, \dots, y_d) \quad \text{with} \quad x_\nu = b^{-L}([i_\nu^1 \dots i_\nu^L]_b + y_\nu).$$

Then we consider functions whose **tensorization at resolution L** are in the **tensor space**

$$\mathbf{V}_L = (\mathbb{R}^b)^{\otimes Ld} \otimes \mathcal{S}^{\otimes d}$$

with $\mathcal{S} \subset \mathbb{R}^{[0,1]}$ some subspace of univariate functions.

If $\mathcal{S} = \mathbb{P}_m$, $\mathbf{V}_L = T_{b,d}^{-1}(\mathbf{V}_L)$ is identified with the space of multivariate splines of degree m over a uniform partition with b^{dL} elements, i.e.

$$\mathbf{V}_L = V_{N_1}^1 \otimes \dots \otimes V_{N_d}^d$$

with $N_1 = \dots = N_d = b^L$ and $V_{N_\nu}^\nu$ a space of univariate splines of degree m over a uniform partition with $N_\nu = b^L$ intervals.

Approximation tools based on tree tensor networks

An alternative is to rely on **tensorization** of functions. A d -variate function f is identified with a tensor

$$\mathbf{f} = T_{b,d}(f) \in (\mathbb{R}^b)^{\otimes Ld} \otimes (\mathbb{R}^{[0,1]})^{\otimes d}$$

such that

$$f(x_1, \dots, x_d) = \mathbf{f}(i_1^1, \dots, i_d^1, \dots, i_1^L, \dots, i_d^L, y_1, \dots, y_d) \quad \text{with} \quad x_\nu = b^{-L}([i_\nu^1 \dots i_\nu^L]_b + y_\nu).$$

Then we consider functions whose **tensorization at resolution L** are in the **tensor space**

$$\mathbf{V}_L = (\mathbb{R}^b)^{\otimes Ld} \otimes \mathcal{S}^{\otimes d}$$

with $\mathcal{S} \subset \mathbb{R}^{[0,1]}$ some subspace of univariate functions.

If $\mathcal{S} = \mathbb{P}_m$, $\mathbf{V}_L = T_{b,d}^{-1}(\mathbf{V}_L)$ is identified with the space of multivariate splines of degree m over a uniform partition with b^{dL} elements, i.e.

$$\mathbf{V}_L = V_{N_1}^1 \otimes \dots \otimes V_{N_d}^d$$

with $N_1 = \dots = N_d = b^L$ and $V_{N_\nu}^\nu$ a space of univariate splines of degree m over a uniform partition with $N_\nu = b^L$ intervals.

Note that different resolutions L_ν could be used to tensorize the different variables x_ν .

Approximation tools based on tree tensor networks

Then as an approximation tool, we consider functions f whose tensorization is a tensor network in $\mathcal{T}_r^{T_L}(\mathbf{V}_L)$, with T_L a dimension tree over $\{1, \dots, Ld + d\}$.

Using the tensor train format, the corresponding function $f(x_1, \dots, x_d)$ has the representation

$$f(x_1, \dots, x_d) = \begin{array}{ccccccc} & \boxed{v^1} & \boxed{v^2} & \cdots & \boxed{v^{Ld}} & \boxed{v^{Ld+1}} & \cdots & \boxed{v^{Ld+d}} \\ & | & | & & | & | & & | \\ & i_1^1 & i_2^1 & & i_d^L & \boxed{\phi_S} & & \boxed{\phi_S} \\ & & & & & | & & | \\ & & & & & y_1 & & y_d \end{array}$$

with ϕ_S the feature map associated with S . This is similar to the [quantized tensor train \(QTT\)](#) format [Kazeev, Khoromskij, Oseledets, Schwab, ...]

Later on, we consider $S = \mathbb{P}_m$ and $\phi_S(y) = (1, y, \dots, y^{m+1})$ or any other polynomial basis.

An **approximation tool** $\Phi = (\Phi_n)_{n \in \mathbb{N}}$ is then defined by

$$\Phi_n = \{f \in \Phi_{L, T_L, r} : L \in \mathbb{N}_0, r \in \mathbb{N}^{T_L}, \text{compl}(f) \leq n\}$$

with $\Phi_{L, T_L, r}$ the functions whose tensorization at resolution L is in $\mathcal{T}_r^{T_L}(V_L)$.

The **resolution L and ranks r are free parameters**, and **compl**(\cdot) is some **complexity measure**.

Complexity measures and corresponding approximation tools

The complexity $\text{compl}(f)$ of f is defined as the complexity of the associated tensor network $\mathbf{v} = \{v^\alpha\}_{\alpha \in T}$.

- **Number of parameters** (full tensors network)

$$\text{compl}_{\mathcal{F}}(f) = \sum_{\alpha} \text{number_of_entries}(v^\alpha)$$

- **Number of non-zero parameters** (sparse tensors network)

$$\text{compl}_{\mathcal{S}}(f) = \sum_{\alpha} \|v^\alpha\|_0$$

Complexity measures and corresponding approximation tools

The complexity $\text{compl}(f)$ of f is defined as the complexity of the associated tensor network $\mathbf{v} = \{v^\alpha\}_{\alpha \in T}$.

- **Number of parameters** (full tensors network)

$$\text{compl}_{\mathcal{F}}(f) = \sum_{\alpha} \text{number_of_entries}(v^\alpha)$$

- **Number of non-zero parameters** (sparse tensors network)

$$\text{compl}_{\mathcal{S}}(f) = \sum_{\alpha} \|v^\alpha\|_0$$

Complexity measures $\text{compl}_{\mathcal{F}}$ and $\text{compl}_{\mathcal{S}}$ yield two different approximation tools

$$\Phi_n^{\mathcal{F}} \quad \text{and} \quad \Phi_n^{\mathcal{S}}$$

such that

$$\Phi_n^{\mathcal{F}} \subset \Phi_n^{\mathcal{S}}$$

Approximation with tree tensor networks

Given a function f from a Banach space X , the **best approximation error** of f by an element of Φ_n is

$$E(f, \Phi_n)_X := \inf_{g \in \Phi_n} \|f - g\|_X$$

Fundamental questions are:

- does $E(f, \Phi_n)_X$ converge to 0 for any f ?
(**universality**)
- does a best approximation exist ?
(**proximality**)
- how fast does it converge for functions from classical function classes ?
(**expressivity**)
- what are the functions for which $E(f, \Phi_n)_X$ converges with some given rate ?
(**characterization of approximation classes**)

Approximation with tree tensor networks

Given a function f from a Banach space X , the **best approximation error** of f by an element of Φ_n is

$$E(f, \Phi_n)_X := \inf_{g \in \Phi_n} \|f - g\|_X$$

Fundamental questions are:

- does $E(f, \Phi_n)_X$ converge to 0 for any f ?
(**universality**)
- does a best approximation exist ?
(**proximality**)
- how fast does it converge for functions from classical function classes ?
(**expressivity**)
- what are the functions for which $E(f, \Phi_n)_X$ converges with some given rate ?
(**characterization of approximation classes**)

Another fundamental problem (addressed later) is to provide **algorithms** to practically compute approximations using available information on the function (model equations, samples...)

Outline

- 1 Approximation tools based on tree tensor networks
- 2 Universality, Proximality and Expressivity**
- 3 Choice of tensor formats
- 4 Approximation classes of tree tensor networks

Universality

First note that for any algebraic feature tensor space V , and any tree T ,

$$\bigcup_r \mathcal{T}_r^T(V) = V.$$

so the question of universality of tree tensor networks boils down to conditions on the tensor feature spaces.

Universality

First note that for any algebraic feature tensor space V , and any tree T ,

$$\bigcup_r \mathcal{T}_r^T(V) = V.$$

so the question of universality of tree tensor networks boils down to conditions on the tensor feature spaces.

- Consider the first family of approximation tools with variable feature spaces V_N , $N \in \mathbb{N}^d$.

If $\bigcup_N V_N$ is dense in X , then the tools are universal for functions in X .

In particular, this is true for $X = L^p((0, 1)^d)$, $p < \infty$, and for polynomial or splines spaces V_N .

Universality

First note that for any algebraic feature tensor space V , and any tree T ,

$$\bigcup_r \mathcal{T}_r^T(V) = V.$$

so the question of universality of tree tensor networks boils down to conditions on the tensor feature spaces.

- Consider the first family of approximation tools with variable feature spaces V_N , $N \in \mathbb{N}^d$.

If $\bigcup_N V_N$ is dense in X , then the tools are universal for functions in X .

In particular, this is true for $X = L^p((0, 1)^d)$, $p < \infty$, and for polynomial or splines spaces V_N .

- Consider the second family of approximation tools using tensorization.

If $\bigcup_L V_L$ is dense in X , then the tools are universal for functions in X .

In particular, this is true for $X = L^p((0, 1)^d)$, $p < \infty$, assuming that S contains the function one.

For any tree T , any T -rank r , and any finite dimensional tensor space V of X , $\mathcal{T}_r^T(V)$ is a closed set in V .

Φ_n is a finite union of such sets, all contained in a single finite dimensional space V^* .
Then Φ_n is a closed set of a finite dimensional space V^* and is therefore proximal in X .

Different ways to analyse the expressivity of tree tensor networks

- Exploit known results on other approximation tools and estimate the complexity to encode these tools using tree tensor networks.
- Directly encode a function using tree tensor networks (with controlled errors)
- Analyse the convergence of bilinear approximations

$$u(x_\alpha, x_{\alpha^c}) \approx \sum_{k=1}^{r_\alpha} u_k^\alpha(x_\alpha) u_k^{\alpha^c}(x_{\alpha^c})$$

or the approximability of partial evaluations $u(\cdot, x_{\alpha^c})$ by linear approximation spaces of dimension r_α

Approximation of functions from smoothness classes

We consider **approximation tools based on tensorization** and functions from classical smoothness classes:

- Sobolev and Besov functions
- Analytic functions
- Analytic functions with singularities

Approximation of functions from Besov spaces $B_q^\alpha(L^p)$

From results on [spline approximation](#) and their [encoding with tensor networks](#), we obtain

Theorem

Let $f \in B_\infty^\alpha(L^p)$ with $\alpha > 0$ and $0 < p \leq \infty$. Then

$$E(f, \Phi_n^{\mathcal{F}})_{L^p} \leq C n^{-\tilde{\alpha}/d} \|f\|_{B_\infty^\alpha(L^p)}$$

for arbitrary $\tilde{\alpha} < \alpha$.

- Tensor networks achieve (near to) **optimal performance for any Besov regularity order** (measured in L^p norm).
- They perform as well as optimal linear approximation tools (e.g. splines), **without requiring to adapt the tool to the regularity order α** .
- **The depth (resolution L) of the network is crucial to capture extra regularity.**

Approximation of functions from Besov spaces $B_q^\alpha(L^\tau)$

Now consider the much harder problem of approximating functions from Besov spaces $B_q^\alpha(L^\tau)$ where regularity is measured in a L^τ -norm weaker than L^p -norm.

From results on best n -term approximation using dilated splines, we obtain

Theorem

Let $f \in B_q^\alpha(L^\tau)$ with $\alpha > 0$, $0 < q \leq \tau < p < \infty$, $1 \leq p < \infty$ and

$$\frac{\alpha}{d} > \frac{1}{\tau} - \frac{1}{p}.$$

Then

$$E(f, \Phi_n^S)_{L^p} \leq Cn^{-\alpha'/d} |f|_{B_q^\alpha(L^\tau)}, \quad E(f, \Phi_n^F)_{L^p} \leq Cn^{-\alpha'/(2d)} |f|_{B_q^\alpha(L^\tau)},$$

for arbitrary $\alpha' < \alpha$.

Approximation of functions from Besov spaces $B_q^\alpha(L^\tau)$

Now consider the much harder problem of approximating functions from Besov spaces $B_q^\alpha(L^\tau)$ where regularity is measured in a L^τ -norm weaker than L^p -norm.

From results on [best \$n\$ -term approximation using dilated splines](#), we obtain

Theorem

Let $f \in B_q^\alpha(L^\tau)$ with $\alpha > 0$, $0 < q \leq \tau < p < \infty$, $1 \leq p < \infty$ and

$$\frac{\alpha}{d} > \frac{1}{\tau} - \frac{1}{p}.$$

Then

$$E(f, \Phi_n^S)_{L^p} \leq Cn^{-\alpha'/d} |f|_{B_q^\alpha(L^\tau)}, \quad E(f, \Phi_n^F)_{L^p} \leq Cn^{-\alpha'/(2d)} |f|_{B_q^\alpha(L^\tau)},$$

for arbitrary $\alpha' < \alpha$.

Approximation of functions from Besov spaces $B_q^\alpha(L^\tau)$

Now consider the much harder problem of approximating functions from Besov spaces $B_q^\alpha(L^\tau)$ where regularity is measured in a L^τ -norm weaker than L^p -norm.

From results on best n -term approximation using dilated splines, we obtain

Theorem

Let $f \in B_q^\alpha(L^\tau)$ with $\alpha > 0$, $0 < q \leq \tau < p < \infty$, $1 \leq p < \infty$ and

$$\frac{\alpha}{d} > \frac{1}{\tau} - \frac{1}{p}.$$

Then

$$E(f, \Phi_n^S)_{L^p} \leq Cn^{-\alpha'/d} |f|_{B_q^\alpha(L^\tau)}, \quad E(f, \Phi_n^F)_{L^p} \leq Cn^{-\alpha'/(2d)} |f|_{B_q^\alpha(L^\tau)},$$

for arbitrary $\alpha' < \alpha$.

- Sparse tensor networks achieve arbitrarily close to optimal rates in $O(n^{-\alpha/d})$ for functions with any Besov smoothness α (measured in L^τ norm), without the need to adapt the tool to the regularity order α .
- Here depth and sparsity are crucial for obtaining near to optimal performance.
- Full tensor networks have slightly lower performance in $O(n^{-\alpha/(2d)})$.

Analytic functions

For function $f : [0, 1]$ with analytic extension on an open complex domain

$$D_\rho = \{z \in \mathbb{C} : \text{dist}(z, [0, 1]) < \frac{\rho - 1}{2}\}, \quad \rho > 1,$$

we obtain an exponential convergence

$$E(f, \Phi_n^{\mathcal{F}})_{L^\infty} \leq C\gamma^{-n^{1/3}},$$

with $\gamma = \min\{\rho, b^{(m+1)/b}\}$.

Analytic functions

For function $f : [0, 1]$ with analytic extension on an open complex domain

$$D_\rho = \{z \in \mathbb{C} : \text{dist}(z, [0, 1]) < \frac{\rho - 1}{2}\}, \quad \rho > 1,$$

we obtain an exponential convergence

$$E(f, \Phi_n^{\mathcal{F}})_{L^\infty} \leq C\gamma^{-n^{1/3}},$$

with $\gamma = \min\{\rho, b^{(m+1)/b}\}$.

The proof relies on the approximation of analytic functions with polynomials and the encoding of polynomials with tree tensor networks: a chebychev polynomial p of degree \bar{m} is such that

$$\|f - p\|_{L^\infty} \leq \frac{2}{\rho - 1} \|f\|_{L^\infty(D_\rho)} \rho^{-\bar{m}}$$

A polynomial of degree \bar{m} can be approximated by φ in $\Phi_{L,r,\bar{m}}$ with an error in $O(b^{-L(m+1)})$, so that

$$\|f - \varphi\|_{L^\infty} \lesssim \rho^{-\bar{m}} + b^{-L(m+1)}$$

We obtain the result by choosing $\bar{m} \sim n^{1/3}$ and $L \sim b^{-1}n^{1/3}$, so that $\text{compl}_{\mathcal{F}}(\varphi) \leq n$.

Functions with singularities

Consider the approximation $u(x) = x^\alpha$, $0 < \alpha \leq 1$, in L^∞ .

- Piecewise constant linear approximation.

$$u \in B_\infty^\alpha(L^\infty), \quad u \notin B_\infty^\beta(L^\infty) \quad \text{for } \beta > \alpha,$$

and a piecewise constant approximation on a uniform mesh with n elements gives a convergence in $O(n^{-\alpha})$ in L^∞ ,

Functions with singularities

Consider the approximation $u(x) = x^\alpha$, $0 < \alpha \leq 1$, in L^∞ .

- Piecewise constant linear approximation.

$$u \in B_\infty^\alpha(L^\infty), \quad u \notin B_\infty^\beta(L^\infty) \quad \text{for } \beta > \alpha,$$

and a piecewise constant approximation on a uniform mesh with n elements gives a convergence in $O(n^{-\alpha})$ in L^∞ ,

- Piecewise constant nonlinear approximation.

$$u \in BV \subset B_\infty^1(L^1),$$

and a piecewise constant approximation on an optimal mesh with n elements gives a convergence in $O(n^{-1})$ in L^∞ ,

Functions with singularities

Consider the approximation $u(x) = x^\alpha$, $0 < \alpha \leq 1$, in L^∞ .

- Piecewise constant linear approximation.

$$u \in B_\infty^\alpha(L^\infty), \quad u \notin B_\infty^\beta(L^\infty) \quad \text{for } \beta > \alpha,$$

and a piecewise constant approximation on a uniform mesh with n elements gives a convergence in $O(n^{-\alpha})$ in L^∞ ,

- Piecewise constant nonlinear approximation.

$$u \in BV \subset B_\infty^1(L^1),$$

and a piecewise constant approximation on an optimal mesh with n elements gives a convergence in $O(n^{-1})$ in L^∞ ,

- Piecewise constant approximation and tensor networks.

A piecewise constant approximation on a uniform mesh with 2^d elements exploiting low-rank structures gives an exponential convergence in $O(\beta^{-n})$, where n is the complexity of the representation. Achieves the performance of h - p methods.

High-dimensional approximation

- For Besov spaces $B_q^\alpha(L^p)$, tensor networks achieve (near to) optimal rate in $O(n^{-\alpha/d})$ which deteriorates with d , that is the curse of dimensionality.

High-dimensional approximation

- For **Besov spaces** $B_q^\alpha(L^p)$, tensor networks achieve (near to) optimal rate in $O(n^{-\alpha/d})$ which deteriorates with d , that is the **curse of dimensionality**.
- For **Besov spaces with mixed smoothness** $MB_q^\alpha(L^p)$, sparse tensor networks achieve near to optimal performance in $O(n^{-\alpha} \log(n)^d)$. But still the **curse of dimensionality**.

High-dimensional approximation

- For **Besov spaces** $B_q^\alpha(L^p)$, tensor networks achieve (near to) optimal rate in $O(n^{-\alpha/d})$ which deteriorates with d , that is the **curse of dimensionality**.
- For **Besov spaces with mixed smoothness** $MB_q^\alpha(L^p)$, sparse tensor networks achieve near to optimal performance in $O(n^{-\alpha} \log(n)^d)$. But still the **curse of dimensionality**.
- For **Besov spaces with anisotropic smoothness** $AB_q^\alpha(L^p)$, sparse tensor networks also achieve near to optimal rates in $O(n^{-s(\alpha)/d})$ with

$$s(\alpha)/d = (\alpha_1^{-1} + \dots + \alpha_d^{-1})^{-1}$$

the aggregated smoothness. Curse of dimensionality can be circumvented with sufficient **anisotropy**.

High-dimensional approximation

- For **Besov spaces** $B_q^\alpha(L^p)$, tensor networks achieve (near to) optimal rate in $O(n^{-\alpha/d})$ which deteriorates with d , that is the **curse of dimensionality**.
- For **Besov spaces with mixed smoothness** $MB_q^\alpha(L^p)$, sparse tensor networks achieve near to optimal performance in $O(n^{-\alpha} \log(n)^d)$. But still the **curse of dimensionality**.
- For **Besov spaces with anisotropic smoothness** $AB_q^\alpha(L^p)$, sparse tensor networks also achieve near to optimal rates in $O(n^{-s(\alpha)/d})$ with

$$s(\alpha)/d = (\alpha_1^{-1} + \dots + \alpha_d^{-1})^{-1}$$

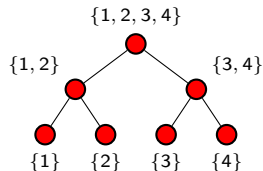
the aggregated smoothness. Curse of dimensionality can be circumvented with sufficient **anisotropy**.

- **Curse of dimensionality can be circumvented** for non usual function classes such as **compositions of smooth functions** (see Bachmayr, Nouy and Schneider 2021).

Compositional functions

Consider a **tree-structured composition of smooth functions** $\{f_\alpha : \alpha \in T\}$, see [Mhaskar, Liao, Poggio 2016] for deep neural networks.

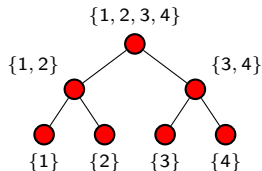
$$f_{1,2,3,4} (f_{1,2} (f_1(x_1), f_2(x_2)), f_{3,4} (f_3(x_3), f_4(x_4)))$$



Compositional functions

Consider a **tree-structured composition of smooth functions** $\{f_\alpha : \alpha \in T\}$, see [Mhaskar, Liao, Poggio 2016] for deep neural networks.

$$f_{1,2,3,4}(f_{1,2}(f_1(x_1), f_2(x_2)), f_{3,4}(f_3(x_3), f_4(x_4))))$$



Assuming that the functions $f_\alpha \in W^{k,\infty}$ with $\|f_\alpha\|_{L^\infty} \leq 1$ and $\|f_\alpha\|_{W^{k,\infty}} \leq B$, the complexity to achieve an accuracy ϵ

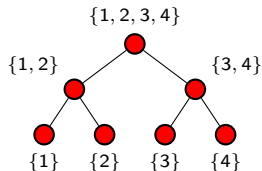
$$C(\epsilon) \lesssim \epsilon^{-3/k} (L+1)^3 B^{3L} d^{1+3/2k}$$

with $L = \log_2(d)$ for a balanced tree and $L+1 = d$ for a linear tree.

Compositional functions

Consider a **tree-structured composition of smooth functions** $\{f_\alpha : \alpha \in T\}$, see [Mhaskar, Liao, Poggio 2016] for deep neural networks.

$$f_{1,2,3,4}(f_{1,2}(f_1(x_1), f_2(x_2)), f_{3,4}(f_3(x_3), f_4(x_4))))$$



Assuming that the functions $f_\alpha \in W^{k,\infty}$ with $\|f_\alpha\|_{L^\infty} \leq 1$ and $\|f_\alpha\|_{W^{k,\infty}} \leq B$, the complexity to achieve an accuracy ϵ

$$C(\epsilon) \lesssim \epsilon^{-3/k} (L+1)^3 B^{3L} d^{1+3/2k}$$

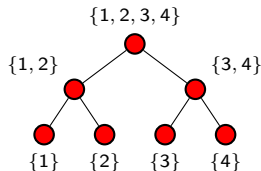
with $L = \log_2(d)$ for a balanced tree and $L+1 = d$ for a linear tree.

- **Bad influence of the depth** through the norm B of functions f_α (roughness).

Compositional functions

Consider a **tree-structured composition of smooth functions** $\{f_\alpha : \alpha \in T\}$, see [Mhaskar, Liao, Poggio 2016] for deep neural networks.

$$f_{1,2,3,4}(f_{1,2}(f_1(x_1), f_2(x_2)), f_{3,4}(f_3(x_3), f_4(x_4))))$$



Assuming that the functions $f_\alpha \in W^{k,\infty}$ with $\|f_\alpha\|_{L^\infty} \leq 1$ and $\|f_\alpha\|_{W^{k,\infty}} \leq B$, the complexity to achieve an accuracy ϵ

$$C(\epsilon) \lesssim \epsilon^{-3/k} (L+1)^3 B^{3L} d^{1+3/2k}$$

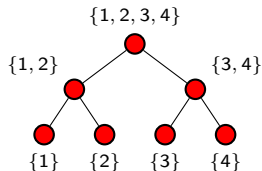
with $L = \log_2(d)$ for a balanced tree and $L+1 = d$ for a linear tree.

- **Bad influence of the depth** through the norm B of functions f_α (roughness).
- For a balanced tree, complexity scales polynomially in d : **no curse of dimensionality** !

Compositional functions

Consider a **tree-structured composition of smooth functions** $\{f_\alpha : \alpha \in T\}$, see [Mhaskar, Liao, Poggio 2016] for deep neural networks.

$$f_{1,2,3,4}(f_{1,2}(f_1(x_1), f_2(x_2)), f_{3,4}(f_3(x_3), f_4(x_4))))$$



Assuming that the functions $f_\alpha \in W^{k,\infty}$ with $\|f_\alpha\|_{L^\infty} \leq 1$ and $\|f_\alpha\|_{W^{k,\infty}} \leq B$, the complexity to achieve an accuracy ϵ

$$C(\epsilon) \lesssim \epsilon^{-3/k} (L+1)^3 B^{3L} d^{1+3/2k}$$

with $L = \log_2(d)$ for a balanced tree and $L+1 = d$ for a linear tree.

- **Bad influence of the depth** through the norm B of functions f_α (roughness).
- For a balanced tree, complexity scales polynomially in d : **no curse of dimensionality** !
- For $B \leq 1$ (and even for **1-Lipschitz** functions), the complexity only scales polynomially in d whatever the tree: **no curse of dimensionality** !

Outline

- 1 Approximation tools based on tree tensor networks
- 2 Universality, Proximality and Expressivity
- 3 Choice of tensor formats**
- 4 Approximation classes of tree tensor networks

Canonical versus tree-based format

Consider a finite dimensional tensor space $V = V^1 \otimes \dots \otimes V^d$ with $\dim(V_\nu) = \mathbb{R}^N$, which is identified with $\mathbb{R}^{N \times \dots \times N}$. Denote by $\mathcal{T}_r^T = \{v : \text{rank}_\alpha(v) \leq r, \alpha \in T\}$.

- From canonical format to tree-based format.

For any v in V and any $\alpha \subset D$, the α -rank is bounded by the canonical rank:

$$\text{rank}_\alpha(v) \leq \text{rank}(v).$$

Therefore, for any tree T ,

$$\mathcal{R}_r \subset \mathcal{T}_r^T,$$

so that an element in \mathcal{R}_r with storage complexity $O(dNr)$ admits a representation in \mathcal{T}_r^T with a storage complexity $O(dNr + dr^{s+1})$ where s is the arity of the tree T .

Canonical versus tree-based format

Consider a finite dimensional tensor space $V = V^1 \otimes \dots \otimes V^d$ with $\dim(V_\nu) = \mathbb{R}^N$, which is identified with $\mathbb{R}^{N \times \dots \times N}$. Denote by $\mathcal{T}_r^T = \{v : \text{rank}_\alpha(v) \leq r, \alpha \in T\}$.

- From canonical format to tree-based format.

For any v in V and any $\alpha \in D$, the α -rank is bounded by the canonical rank:

$$\text{rank}_\alpha(v) \leq \text{rank}(v).$$

Therefore, for any tree T ,

$$\mathcal{R}_r \subset \mathcal{T}_r^T,$$

so that an element in \mathcal{R}_r with storage complexity $O(dNr)$ admits a representation in \mathcal{T}_r^T with a storage complexity $O(dNr + dr^{s+1})$ where s is the arity of the tree T .

- From tree-based format to canonical format. For a balanced or linear binary tree, the subset

$$S = \{v \in \mathcal{T}_r^T : \text{rank}(v) < q^{d/2}\}, \quad q = \min\{N, r\},$$

is of Lebesgue measure 0.

Then a typical element $v \in \mathcal{T}_r^T$ with storage complexity of order $dNr + dr^3$ admits a representation in canonical format with a storage complexity of order $dNq^{d/2}$.

- For some functions, the choice of tree is not crucial. For example, an additive function

$$u_1(x_1) + \dots + u_d(x_d)$$

has α -ranks equal to 2 whatever $\alpha \subset D$.

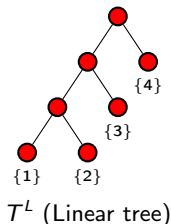
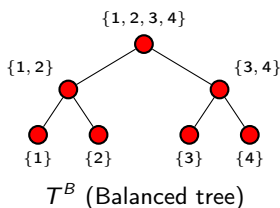
Influence of the tree

- For some functions, the choice of tree is not crucial. For example, an additive function

$$u_1(x_1) + \dots + u_d(x_d)$$

has α -ranks equal to 2 whatever $\alpha \subset D$.

- But usually, different trees lead to different complexities of representations.



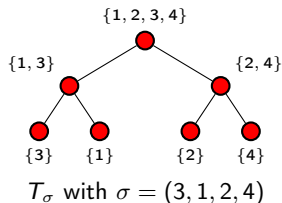
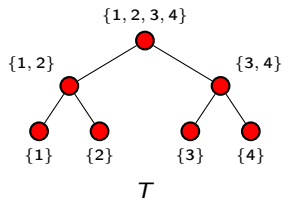
- If $\text{rank}_{T^L}(u) \leq r$ then $\text{rank}_{T^B}(u) \leq r^2$
- If $\text{rank}_{T^B}(u) \leq r$ then $\text{rank}_{T^L}(u) \leq r^{\log_2(d)/2}$

Influence of the tree

Given a tree T and a **permutation** σ of $D = \{1, \dots, d\}$, we define a tree T_σ

$$T_\sigma = \{\sigma(\alpha) : \alpha \in T\}$$

having the same structure as T but different nodes.



If $\text{rank}_T(u) \leq r$ then $\text{rank}_{T_\sigma}(u)$ typically depends on d .

- Consider the Henon-Heiles potential

$$u(x) = \frac{1}{2} \sum_{i=1}^d x_i^2 + 0.2 \sum_{i=1}^{d-1} (x_i x_{i+1}^2 - x_i^3) + \frac{0.2^2}{16} \sum_{i=1}^{d-1} (x_i^2 + x_{i+1}^2)^2$$

Using a linear tree $T = \{\{1\}, \{2\}, \dots, \{d\}, \{1, 2\}, \{1, 2, 3\}, \dots, \{1, \dots, d-1\}, D\}$,

$$\text{rank}_T(u) \leq 4, \quad \text{storage}(u) = O(d)$$

but for the permutation

$$\sigma = (1, 3, \dots, d-1, 2, 4, \dots, d) \quad (*)$$

and the corresponding linear tree T_σ ,

$$\text{rank}_{T_\sigma}(u) \leq 2d + 1, \quad \text{storage}(u) = O(d^3).$$

Influence of the tree

- Consider the Henon-Heiles potential

$$u(x) = \frac{1}{2} \sum_{i=1}^d x_i^2 + 0.2 \sum_{i=1}^{d-1} (x_i x_{i+1}^2 - x_i^3) + \frac{0.2^2}{16} \sum_{i=1}^{d-1} (x_i^2 + x_{i+1}^2)^2$$

Using a linear tree $T = \{\{1\}, \{2\}, \dots, \{d\}, \{1, 2\}, \{1, 2, 3\}, \dots, \{1, \dots, d-1\}, D\}$,

$$\text{rank}_T(u) \leq 4, \quad \text{storage}(u) = O(d)$$

but for the permutation

$$\sigma = (1, 3, \dots, d-1, 2, 4, \dots, d) \quad (*)$$

and the corresponding linear tree T_σ ,

$$\text{rank}_{T_\sigma}(u) \leq 2d + 1, \quad \text{storage}(u) = O(d^3).$$

- For a typical tensor in \mathcal{T}_r^T with T a binary tree, its representation in tree based format with tree T_σ , with σ as in (*), has a **complexity scaling exponentially with d** .

- Consider the probability distribution $f(x) = \mathbb{P}(X = x)$ of a Markov chain $X = (X_1, \dots, X_d)$ given by

$$f(x) = f_1(x_1)f_{2|1}(x_2|x_1) \dots f_{d|d-1}(x_d|x_{d-1})$$

where bivariate functions $f_{i|i-1}$ have a rank r .

- Consider the probability distribution $f(x) = \mathbb{P}(X = x)$ of a Markov chain $X = (X_1, \dots, X_d)$ given by

$$f(x) = f_1(x_1)f_{2|1}(x_2|x_1) \dots f_{d|d-1}(x_d|x_{d-1})$$

where bivariate functions $f_{i|i-1}$ have a rank r .

- With the **linear tree** T containing interior nodes $\{1, 2\}, \{1, 2, 3\}, \dots, \{1, \dots, d-1\}$, f admits a representation in tree-based format with **storage complexity in r^4** .

- Consider the probability distribution $f(x) = \mathbb{P}(X = x)$ of a Markov chain $X = (X_1, \dots, X_d)$ given by

$$f(x) = f_1(x_1)f_{2|1}(x_2|x_1) \dots f_{d|d-1}(x_d|x_{d-1})$$

where bivariate functions $f_{i|i-1}$ have a rank r .

- With the **linear tree** T containing interior nodes $\{1, 2\}, \{1, 2, 3\}, \dots, \{1, \dots, d-1\}$, f admits a representation in tree-based format with **storage complexity in r^4** .
- The **canonical rank** of f is **exponential in d** .

- Consider the probability distribution $f(x) = \mathbb{P}(X = x)$ of a Markov chain $X = (X_1, \dots, X_d)$ given by

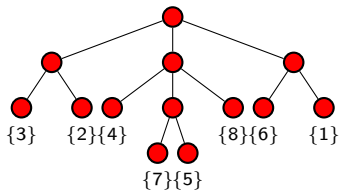
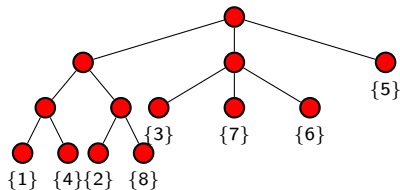
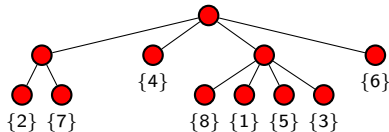
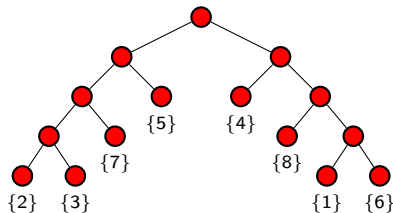
$$f(x) = f_1(x_1)f_{2|1}(x_2|x_1) \dots f_{d|d-1}(x_d|x_{d-1})$$

where bivariate functions $f_{i|i-1}$ have a rank r .

- With the linear tree T containing interior nodes $\{1, 2\}, \{1, 2, 3\}, \dots, \{1, \dots, d-1\}$, f admits a representation in tree-based format with storage complexity in r^4 .
- The canonical rank of f is exponential in d .
- But when considering the linear tree T_σ obtained by applying permutation $\sigma = (1, 3, \dots, d-1, 2, 4, \dots, d)$ to the tree T , the storage complexity in tree-based format is also exponential in d .

How to choose a good tree ?

A combinatorial problem...



Outline

- 1 Approximation tools based on tree tensor networks
- 2 Universality, Proximality and Expressivity
- 3 Choice of tensor formats
- 4 Approximation classes of tree tensor networks

Properties of tree tensor networks

We here consider approximation tools based on tensor networks with tensorized functions (with or without sparsity).

They satisfy

(P1) $\Phi_0 = \{0\}$, $0 \in \Phi_n$

(P2) $a\Phi_n = \Phi_n$ for any $a \in \mathbb{R} \setminus \{0\}$ (cone)

(P3) $\Phi_n \subset \Phi_{n+1}$ (nestedness)

(P4) $\Phi_n + \Phi_n \subset \Phi_{cn}$ for some constant c (not too nonlinear)

Properties of tree tensor networks

We here consider approximation tools based on tensor networks with tensorized functions (with or without sparsity).

They satisfy

- (P1) $\Phi_0 = \{0\}$, $0 \in \Phi_n$
- (P2) $a\Phi_n = \Phi_n$ for any $a \in \mathbb{R} \setminus \{0\}$ (cone)
- (P3) $\Phi_n \subset \Phi_{n+1}$ (nestedness)
- (P4) $\Phi_n + \Phi_n \subset \Phi_{cn}$ for some constant c (not too nonlinear)

For $X = L^p$, they further satisfy

- (P5) $\bigcup_n \Phi_n$ is dense in L^p for $0 < p < \infty$ (universality),
- (P6) for each $f \in L^p$ for $0 < p \leq \infty$, there exists a best approximation in Φ_n (proximal sets).

Approximation classes

For an approximation tool $\Phi = (\Phi_n)_{n \in \mathbb{N}}$, we define for any $\alpha > 0$ the approximation class

$$A_\infty^\alpha(L^p) := A_\infty^\alpha(L^p, \Phi)$$

of functions $f \in L^p$ such that

$$E(f, \Phi_n)_{L^p} \leq Cn^{-\alpha}$$

Approximation classes

For an approximation tool $\Phi = (\Phi_n)_{n \in \mathbb{N}}$, we define for any $\alpha > 0$ the approximation class

$$A_\infty^\alpha(L^p) := A_\infty^\alpha(L^p, \Phi)$$

of functions $f \in L^p$ such that

$$E(f, \Phi_n)_{L^p} \leq Cn^{-\alpha}$$

- Properties (P1)-(P4) of Φ imply that $A_\infty^\alpha(L^p)$ is a quasi-Banach spaces with quasi-seminorm

$$|f|_{A_\infty^\alpha} := \sup_{n \geq 1} n^\alpha E(f, \Phi_n)_{L^p}$$

Approximation classes

For an approximation tool $\Phi = (\Phi_n)_{n \in \mathbb{N}}$, we define for any $\alpha > 0$ the approximation class

$$A_\infty^\alpha(L^p) := A_\infty^\alpha(L^p, \Phi)$$

of functions $f \in L^p$ such that

$$E(f, \Phi_n)_{L^p} \leq Cn^{-\alpha}$$

- Properties (P1)-(P4) of Φ imply that $A_\infty^\alpha(L^p)$ is a quasi-Banach spaces with quasi-seminorm

$$|f|_{A_\infty^\alpha} := \sup_{n \geq 1} n^\alpha E(f, \Phi_n)_{L^p}$$

- Full and sparse complexity measures yield two different approximation spaces

$$\mathcal{F}_\infty^\alpha(L^p) = A_\infty^\alpha(L^p, \Phi^{\mathcal{F}}), \quad \mathcal{S}_\infty^\alpha(L^p) = A_\infty^\alpha(L^p, \Phi^{\mathcal{S}})$$

such that

$$\mathcal{F}_\infty^\alpha(L^p) \hookrightarrow \mathcal{S}_\infty^\alpha(L^p) \hookrightarrow \mathcal{F}_\infty^{\alpha/2}(L^p)$$

Direct embeddings

From results on the approximation properties for Besov spaces, we have the following results.

- Let $\alpha > 0$ and $0 < p \leq \infty$. For arbitrary $\tilde{\alpha} < \alpha$,

$$B_q^\alpha(L^p) \hookrightarrow \mathcal{F}_q^{\tilde{\alpha}/d}(L^p)$$

and

$$MB_q^\alpha(L^p) \hookrightarrow \mathcal{S}_q^{\tilde{\alpha}}(L^p).$$

For arbitrary $\tilde{s} < s(\alpha) := d(\alpha_1^{-1} + \dots + \alpha_d^{-1})^{-1}$,

$$AB_q^\alpha(L^p) \hookrightarrow \mathcal{S}_q^{\tilde{s}/d}(L^p)$$

- For $\alpha > 0$, $1 \leq p < \infty$, $0 < q \leq \tau < p < \infty$ and $\frac{\alpha}{d} > \frac{1}{\tau} - \frac{1}{p}$,

$$B_q^\alpha(L^\tau) \hookrightarrow \mathcal{S}_\infty^{\tilde{\alpha}/d}(L^p) \hookrightarrow \mathcal{F}_\infty^{\tilde{\alpha}/(2d)}(L^p)$$

for arbitrary $\tilde{\alpha} < \alpha$, and similar results for anisotropic and mixed smoothness.

No inverse embedding

For any $\alpha > 0$, $q \leq \infty$, and any β ,

$$\mathcal{F}_\infty^\alpha(L^p) \not\hookrightarrow B_\infty^\beta(L^p).$$

That means that approximation classes contain functions that have **no smoothness in a classical sense**.

Tensor networks may be useful for the **approximation of functions beyond standard smoothness classes**.

- What are the properties of the approximation tool with free tree

$$\Phi_n = \{f \in \Phi_{L, T_L, r} : L \in \mathbb{N}_0, T_L \subset 2^{\{1, \dots, (L+1)d\}}, r \in \mathbb{N}^{\#T}, \text{compl}(f) \leq n\}$$

Higher expressivity (or larger approximation classes) but how much higher ?

- What are the properties of the approximation tool with free tree

$$\Phi_n = \{f \in \Phi_{L, T_L, r} : L \in \mathbb{N}_0, T_L \subset 2^{\{1, \dots, (L+1)d\}}, r \in \mathbb{N}^{\#T}, \text{compl}(f) \leq n\}$$

Higher expressivity (or larger approximation classes) but how much higher ?

- What about expressivity and approximation classes of more general tensor networks ?

References I



M. Ali and A. Nouy.

Approximation with tensor networks. part i: Approximation spaces.
[ArXiv](#), [abs/2007.00118](#), 2020.



M. Ali and A. Nouy.

Approximation with tensor networks. part ii: Approximation rates for smoothness classes.
[ArXiv](#), [abs/2007.00128](#), 2020.



M. Ali and A. Nouy.

Approximation with tensor networks. part iii: Multivariate approximation.
[ArXiv](#), [abs/2007.00128](#), 2020.



M. Bachmayr, A. Nouy and R. Schneider.

Approximation power of tree tensor networks for compositional functions.
In preparation.



R. A. DeVore and G. G. Lorentz.

Constructive approximation, volume 303.
Springer Science & Business Media, 1993.



L. Grasedyck.

Polynomial approximation in hierarchical Tucker format by vector-tensorization.
Inst. für Geometrie und Praktische Mathematik, 2010.



V. Kazeev and C. Schwab.

Approximation of singularities by quantized-tensor fem.
PAMM, 15(1):743–746, 2015.



V. Kazeev, I. Oseledets, M. Rakhuba, and C. Schwab.

Qtt-finite-element approximation for multiscale problems i: model problems in one dimension.
Advances in Computational Mathematics, 43(2):411–442, Apr 2017.



R. Schneider and A. Uschmajew.

Approximation rates for the hierarchical tensor format in periodic sobolev spaces.
Journal of Complexity, 30(2):56 – 71, 2014.